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From an overall free-body diagram, the equations of equilibrium give

$$\circlearrowleft \Sigma M_A = 0 :$$

$$\begin{aligned} & (1.8 \cos 30^\circ)P - (0.9 \sin 30^\circ)(2) \\ & - (2.7 \sin 30^\circ + 0.6 \sin 30^\circ)(1) \\ & - (2.7 \sin 30^\circ + 1.8 \sin 30^\circ + 0.3)(10) = 0 \end{aligned}$$

$$P = 17.99 \text{ kN} \dots\dots\dots \text{Ans.}$$

Next, from a free-body diagram of the bucket,

$$\rightarrow \Sigma F_x = 0 : \quad G_x - T_{EI} = 0$$

$$\uparrow \Sigma F_y = 0 : \quad G_y - 10 = 0$$

$$\circlearrowleft \Sigma M_G = 0 : \quad (1.2 \cos 30^\circ)T_{EI} - 0.3(10) = 0$$

$$T_{EI} = 2.88675 \text{ kN} \cong 2.89 \text{ kN (T)} \dots\dots\dots \text{Ans.}$$

$$G_x = 2.88675 \text{ kN} \quad G_y = 10.00 \text{ kN}$$

Finally, from a free-body diagram of the arm $DEFG$,

$$\rightarrow \Sigma F_x = 0 : \quad (2.88675) - D_x - (2.88675) + F_{BF} \cos \phi = 0$$

$$\uparrow \Sigma F_y = 0 : \quad D_y - (10) - 1 + F_{BF} \sin \phi = 0$$

$$\begin{aligned} \circlearrowleft \Sigma M_D = 0 : \quad & (0.6 \cos 30^\circ)(2.88675) - (0.6 \sin 30^\circ)(1) \\ & + (1.2 \cos 30^\circ)(F_{BF} \cos \phi) + (1.2 \sin 30^\circ)(F_{BF} \sin \phi) \\ & - (1.8 \cos 30^\circ)(2.88675) - (1.8 \sin 30^\circ)(10) = 0 \end{aligned}$$

in which

$$\tan \phi = \frac{1.8 \cos 30^\circ - 1.2 \cos 30^\circ}{1.8 \sin 30^\circ + 1.2 \sin 30^\circ} \quad \phi = 19.107^\circ$$

$$F_{BF} = 10.43807 \text{ kN} \cong 10.44 \text{ kN (C)} \dots\dots\dots \text{Ans.}$$

$$D_x = 9.86303 \text{ kN} \quad D_y = 7.58627 \text{ kN}$$

$$\mathbf{D} = 12.44 \text{ kN } \angle 37.6^\circ \dots\dots\dots \text{Ans.}$$

$$\mathbf{G} = 10.41 \text{ kN } \angle 73.9^\circ \dots\dots\dots \text{Ans.}$$

